

Cloud Mediated Nature Observation

- From Teleoperation to Cloud Robotics

Dez Song
Texas A&M University



Smithsonian

Microsoft

Panasonic

intel.

Thanks to:

Ni Qin, Yiliang Xu, Wen Li, Chang Young Kim, TAMU

Jingtai Liu, Hongpeng Wang, Nankai U

Ken Goldberg, UC Berkeley

Ron Rohrbach, Cornell Lab of Ornithology

John Fitzpatrick, Cornell Lab of Ornithology

David Luneau, U Arkansas

John Rappole, Smithsonian

Selma Glasscock, Welder Wildlife Foundation

National Science Foundation

The Nature Conservancy

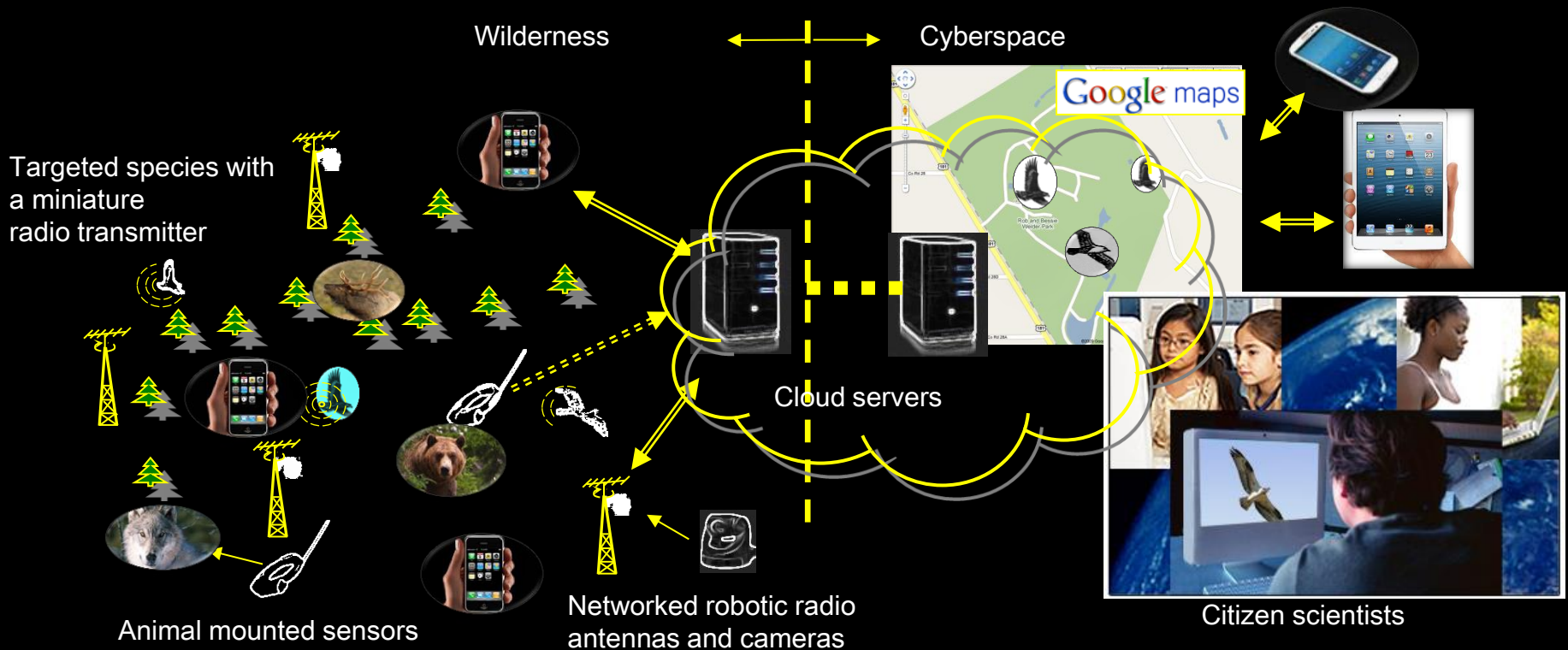
Arkansas Game and Fish Commission

U.S. Fish and Wildlife Service

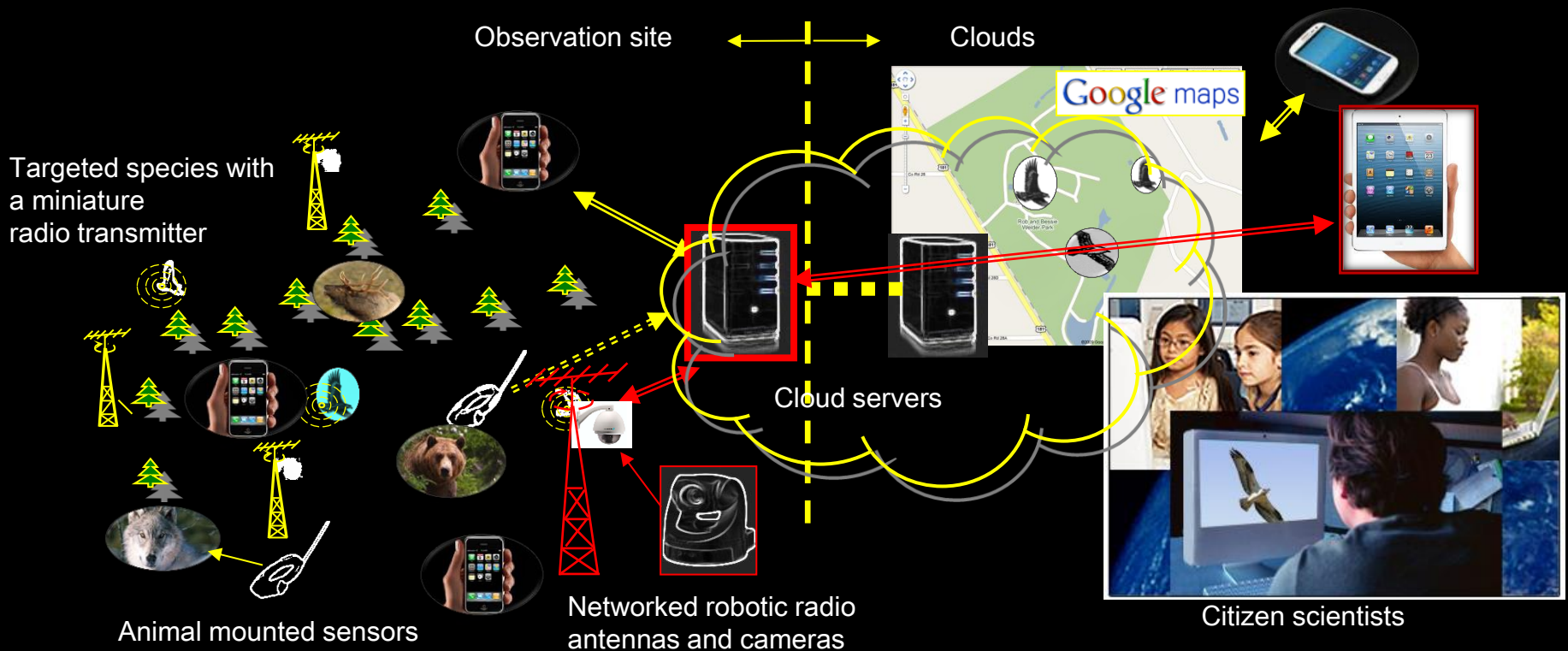
Arkansas Electric Cooperative

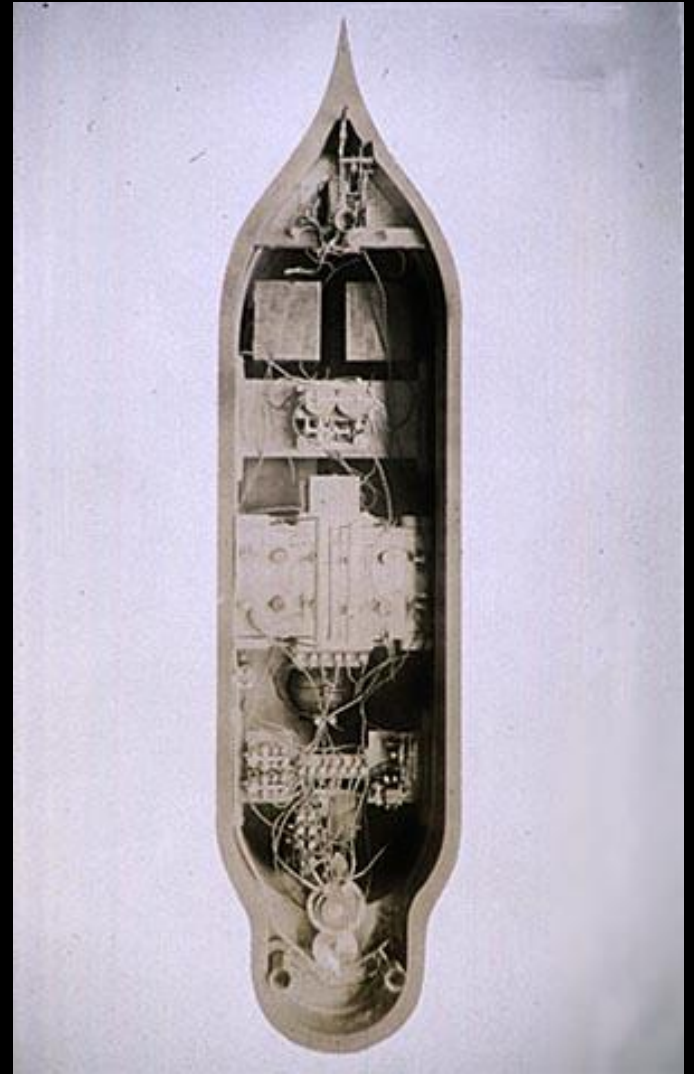
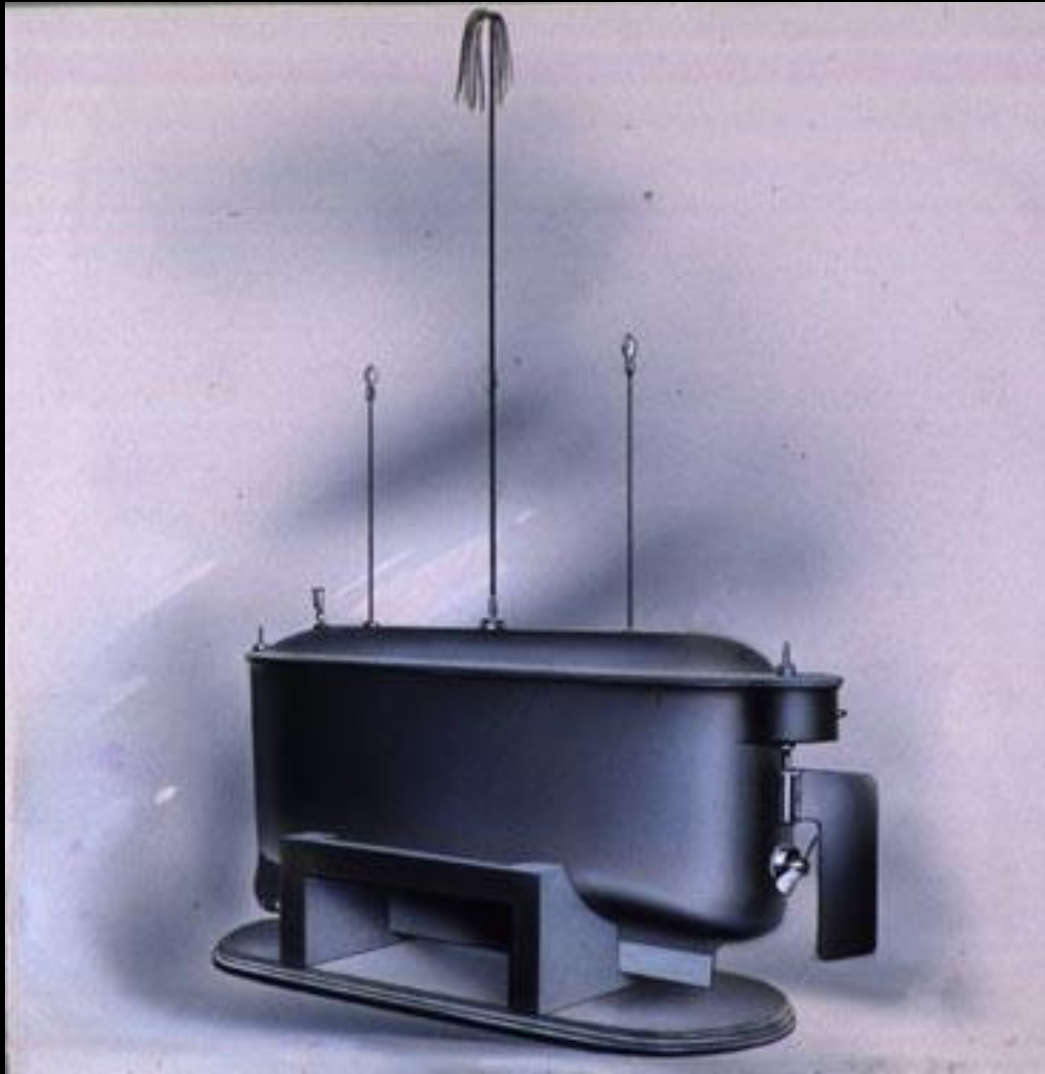
Cache River National Wildlife Refuge

Architecture



Teleoperation

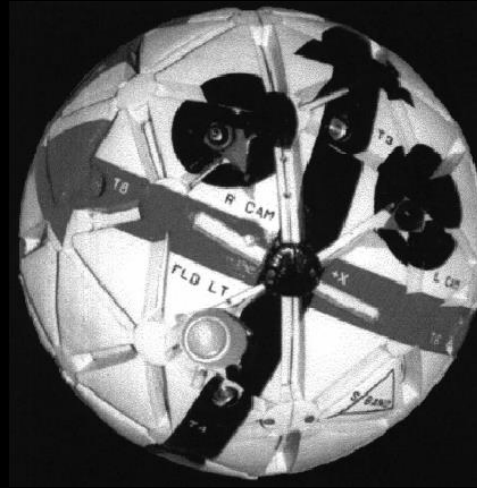


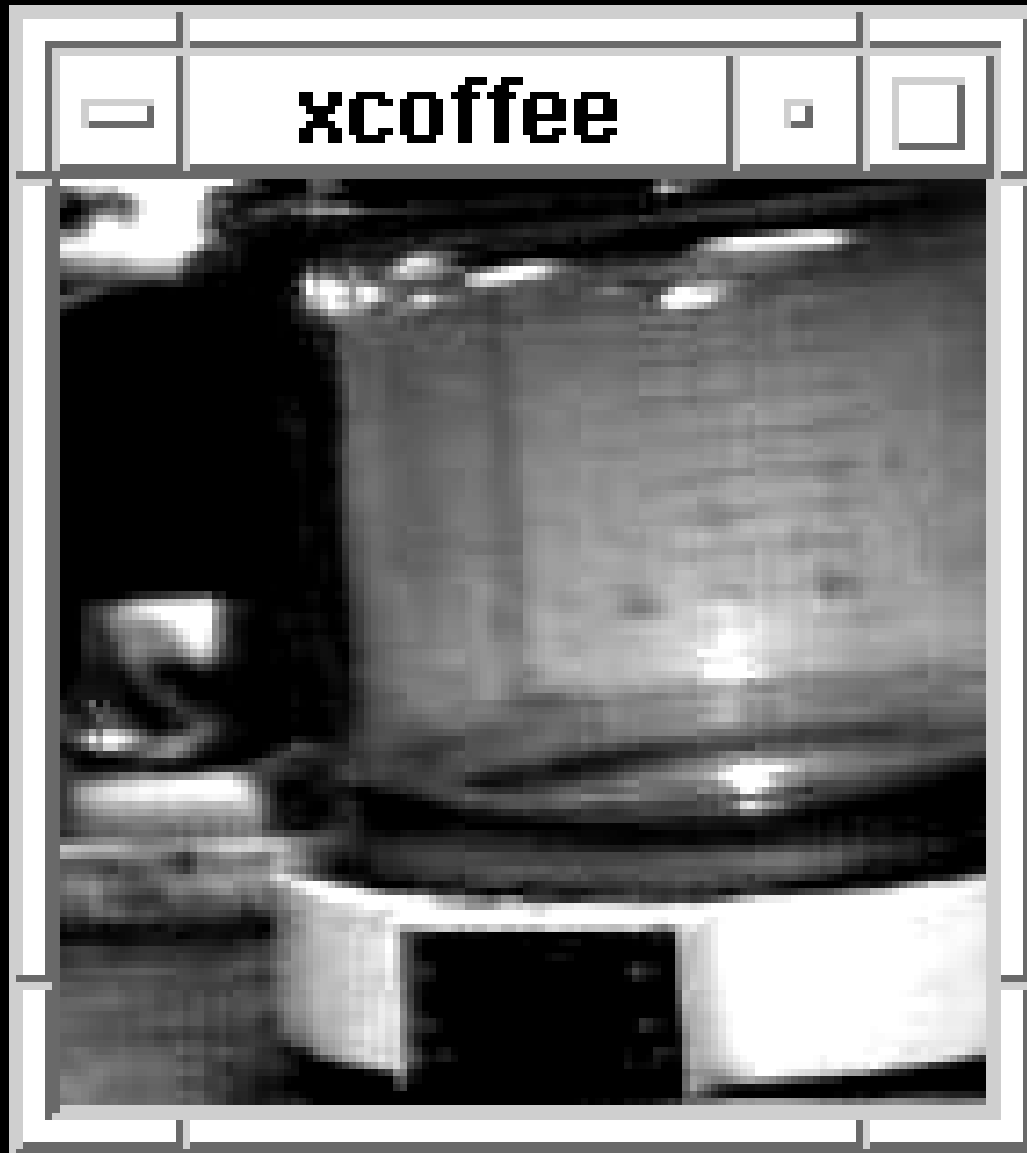


nikola tesla (1898)

teleoperation: related work

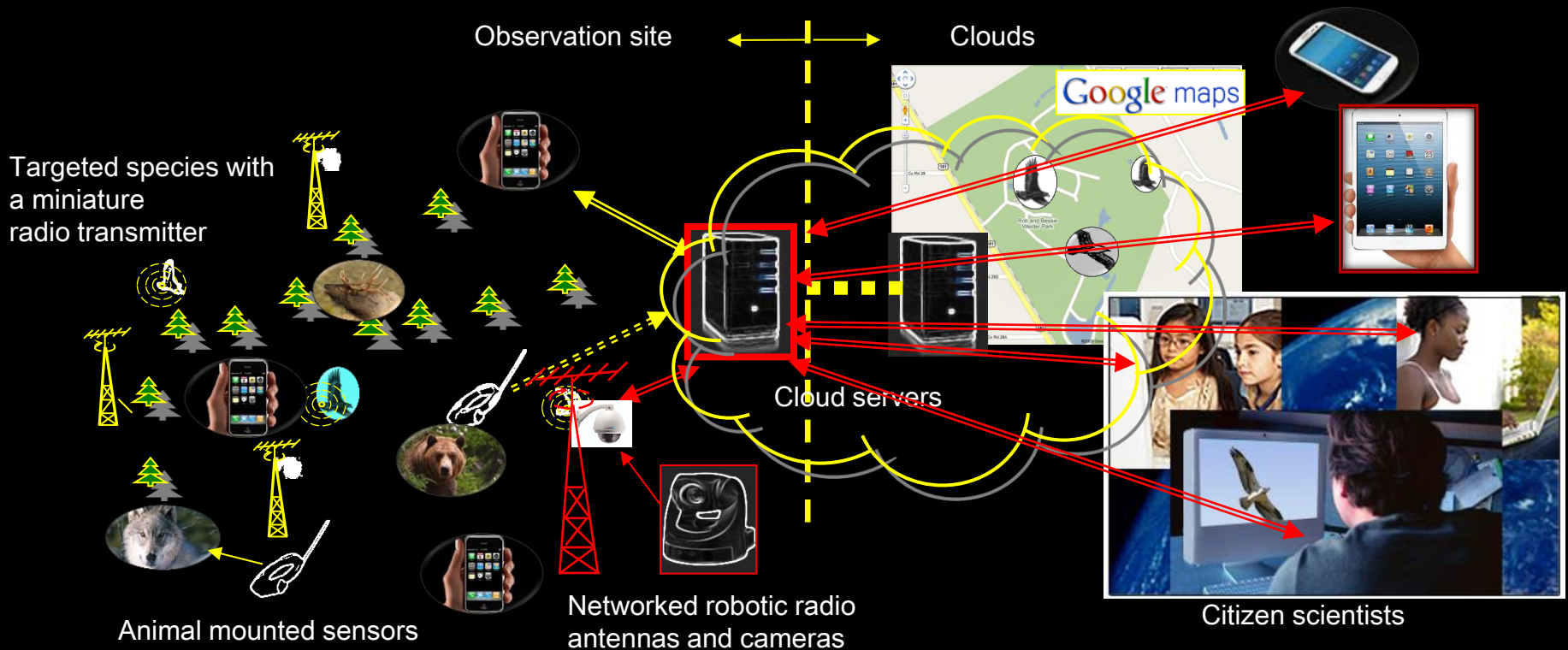
- Tesla, 1898
- Goertz, '54
- Mosher, '64
- Tomovic, '69
- Salisbury, Bejczy, '85
- Ballard, '86
- **Volz, '87**
- Sheridan, '92
- Sato, '94
- Goldberg, '94-
- Presence Journal '92-
- O. Khatib, et al. '96







Collaborative Teleoperation

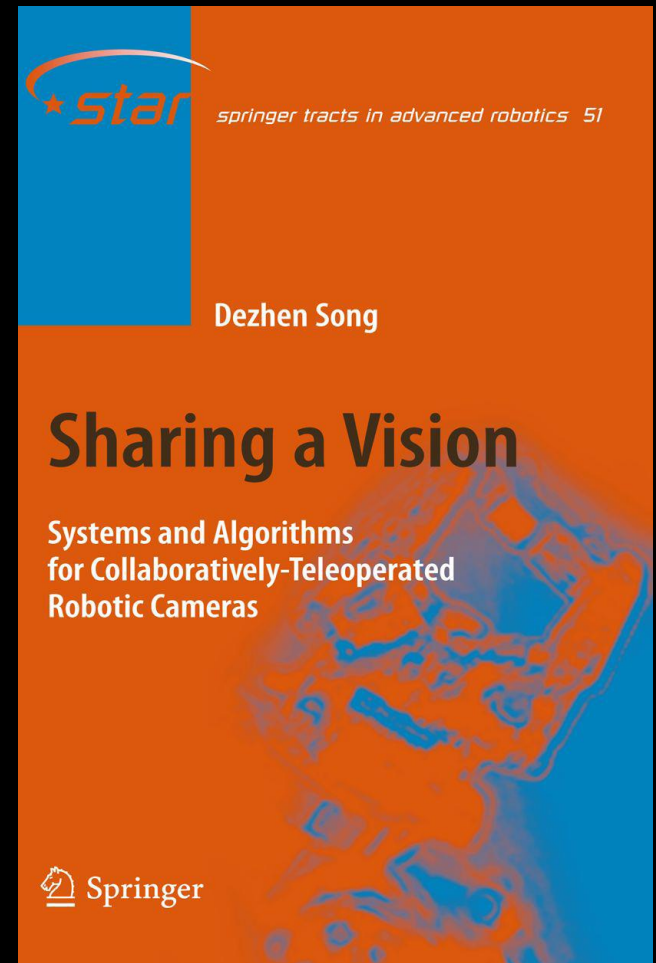




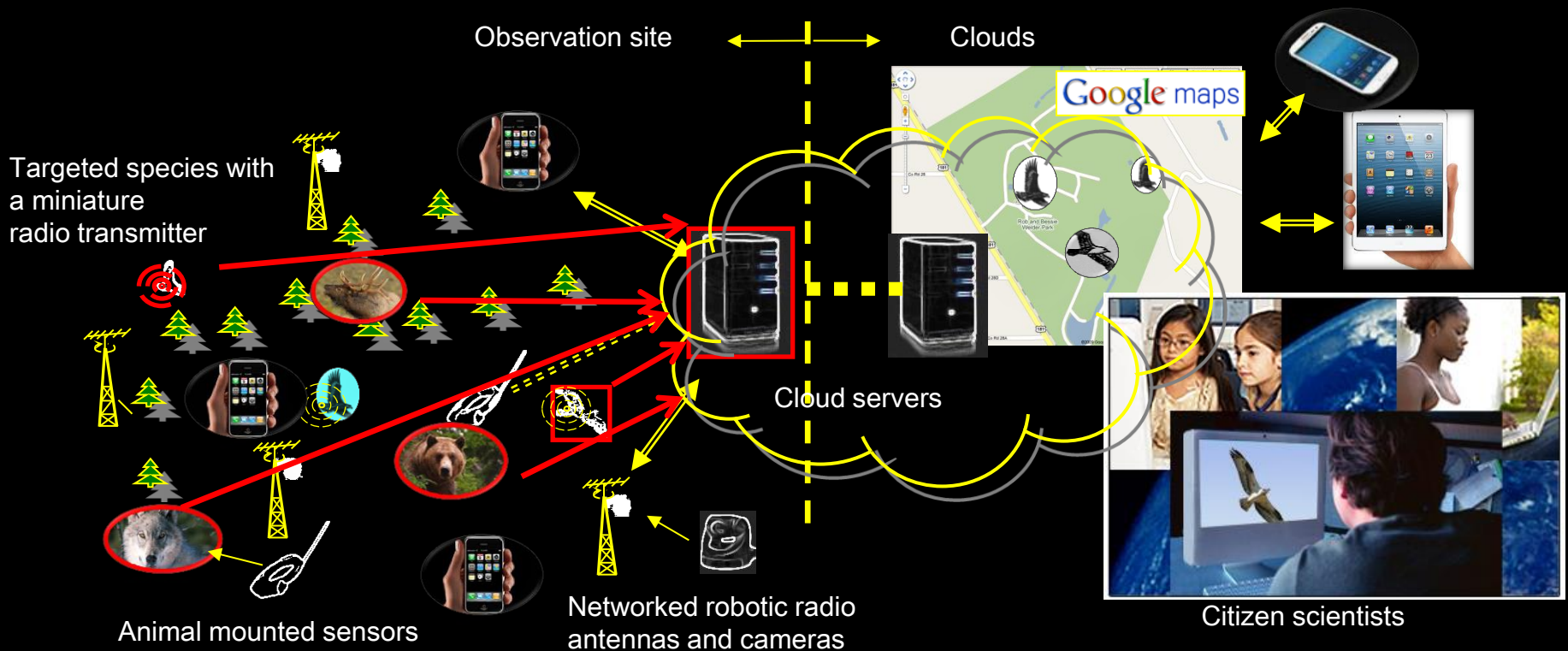
Frame Selection Problem: Given n requests, find optimal frame

frame selection algorithms

Processing	Zoom	Type	Complexity
Centralized	Discrete	Exact	$O(n^2)$
Centralized	Discrete	Approx	$O(nk \log(nk))$, $k=(\log(1/\varepsilon)/\varepsilon)^2$
Centralized	Contin.	Exact	$O(n^3)$
Centralized	Contin.	Approx	$O((n + 1/\varepsilon^3) \log^2 n)$
Distributed	Discrete	Exact	Server: $O(n)$, Client: $O(n)$
Distributed	Contin.	Approx	Server: $O(n)$, Client $O(1/\varepsilon^3)$
p-Frame	Discrete	Approx	$O(n/\varepsilon^3 + p^2/\varepsilon^6)$

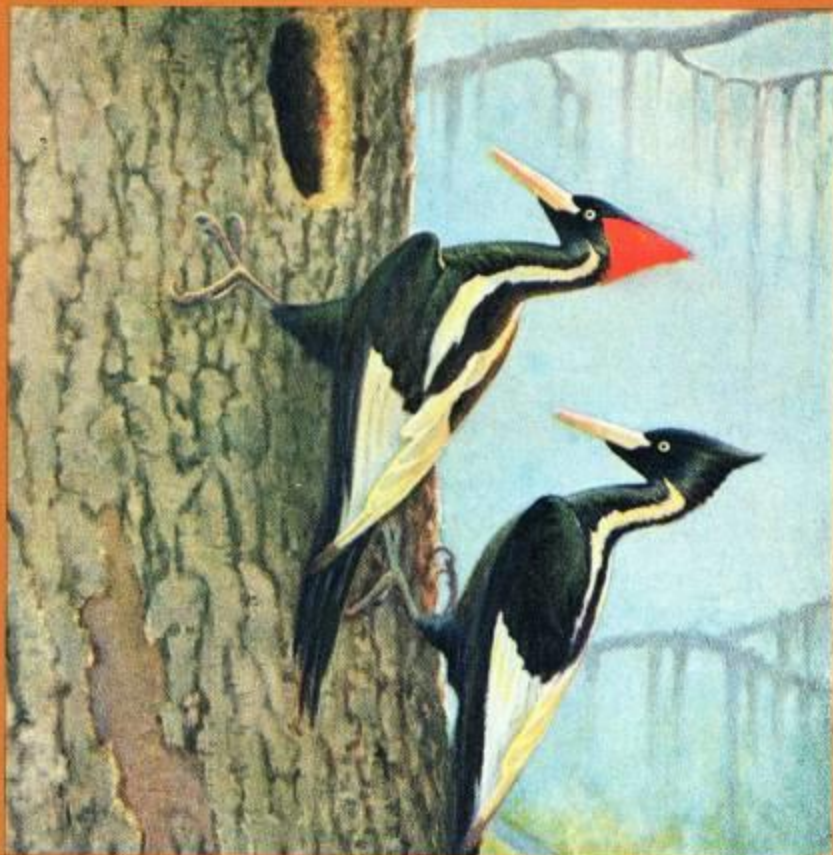


Robotic BioTelemetry





\$2.00



The Ivory-billed Woodpecker

by James T. Tanner



Detecting Rare Birds

- Low occurrence (e.g., <10 times per year)
- Short duration (e.g., < 1 sec. in FOV)
- Huge video data for human identification.
- Setup and maintenance in remote environments.



Natural cameras

- Crittercam
- DeerCam
- Africa web cams at the Tembe Elephant part
- Tiger web cams
- James Reserve Wildlife Observatory
- Crane Cam
- Swan Cam

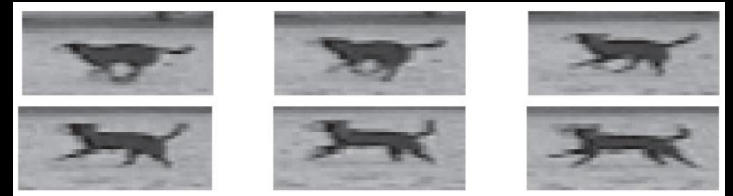


Related Work

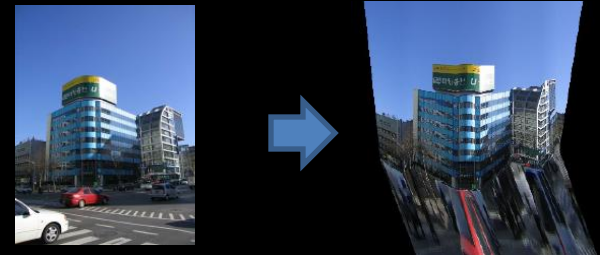
- Motion detection and tracking
 - Elgammal, Grimson, Isard ...



- Periodic motion detection
 - Culter, Ran, Briassouli ...



- 3D inference using monocular vision
 - Ribnick, Hoiem, Saxena ...



Bird detection problem

- Input
 - targeted bird body length l_b and speed range $\mathcal{V}=[v_{\min}, v_{\max}]$.
 - a sequence of n images containing a moving object

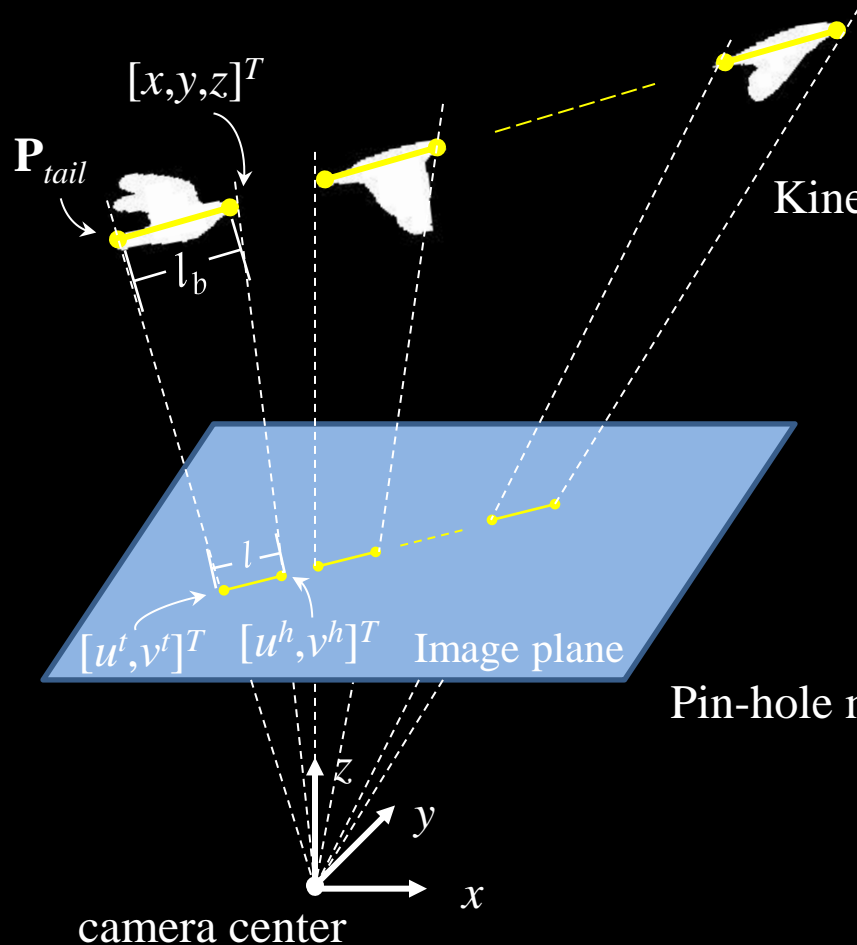


- Output
 - to determine if the object is a bird of targeted species

Conjecture 1: Invariant body length



Modeling A Flying Bird



$$\mathbf{p} = [x, y, z]^T \quad \mathbf{v} = [\dot{x}, \dot{y}, \dot{z}]^T$$

Kinematics: $\dot{\mathbf{x}} = \begin{bmatrix} \dot{\mathbf{p}} \\ \dot{\mathbf{v}} \end{bmatrix} = [\dot{x}, \dot{y}, \dot{z}, 0, 0, 0]^T = \begin{bmatrix} \mathbf{v} \\ \mathbf{0} \end{bmatrix}$

Tail: $\mathbf{P}_{tail} = [x^t, y^t, z^t]^T = \begin{bmatrix} x - \dot{x}l_b / \|\mathbf{v}\| \\ y - \dot{y}l_b / \|\mathbf{v}\| \\ z - \dot{z}l_b / \|\mathbf{v}\| \end{bmatrix}$

Pin-hole model:

$$\mathbf{z} = \begin{bmatrix} fx/z \\ fy/z \\ fx^t/z^t \\ fy^t/z^t \end{bmatrix} = \begin{bmatrix} fx/z \\ fy/z \\ f \frac{x\|\mathbf{v}\| - l_b\dot{x}}{z\|\mathbf{v}\| - l_b\dot{z}} \\ f \frac{y\|\mathbf{v}\| - l_b\dot{y}}{z\|\mathbf{v}\| - l_b\dot{z}} \end{bmatrix} + \mathbf{w}$$

$$:= h(\mathbf{x}) + \mathbf{w}$$

PODS-EKF Approximate Computation

$$\tilde{\mathbf{Z}}^{1:n} = \underset{\mathbf{z}(k) \in \mathcal{S}(k)}{\operatorname{argmin}} \varepsilon(\mathbf{X}^{1:n})$$

Subject to:

$$\hat{\mathbf{x}}(k|k-1) = A(k)\hat{\mathbf{x}}(k-1|k-1),$$

$$\hat{P}(k|k-1) = A(k)\hat{P}(k-1|k-1)A^T(k) + Q(k),$$

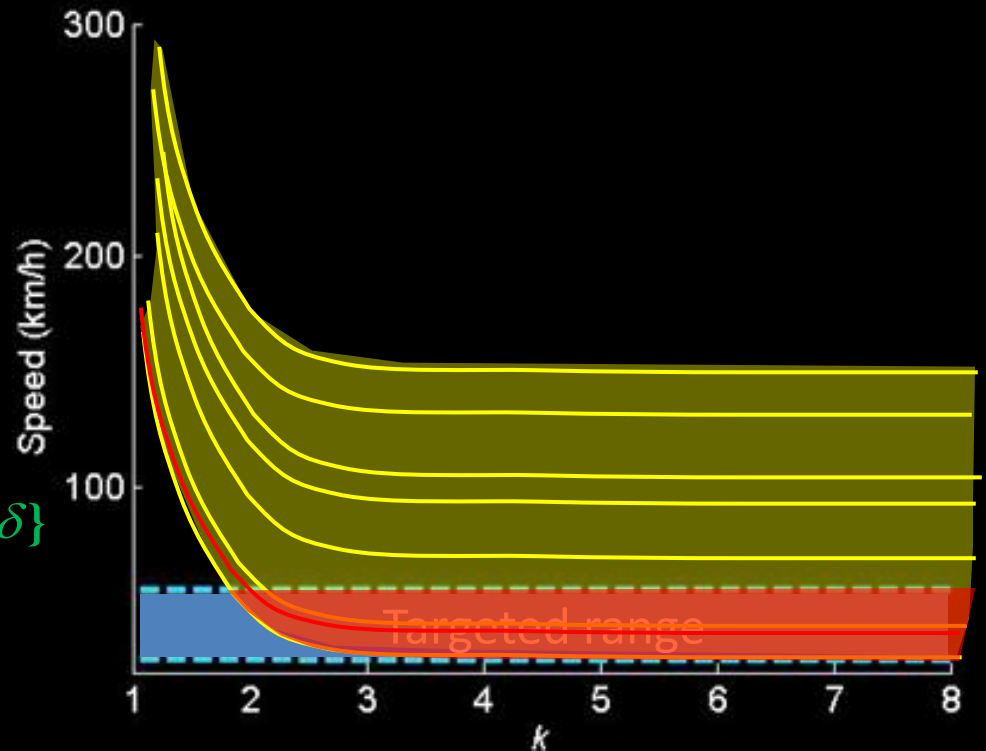
$$K(k) = \frac{\hat{P}(k|k-1)H^T(k)}{H(k)\hat{P}(k|k-1)H^T(k) + W(k)},$$

$$\hat{\mathbf{x}}(k|k) = \hat{\mathbf{x}}(k|k-1) + K(k)(\mathbf{z}(k) - h(\hat{\mathbf{x}}(k|k-1))),$$

$$\hat{P}(k|k) = (\mathbf{I}_{6 \times 6} - K(k)H(k))\hat{P}(k|k-1),$$

$$\mathbf{Z}^{1:n} = \{\mathbf{Z}^{1:n} \mid \mathbf{z}(k) \in \mathcal{S}(k) \text{ and } \varepsilon(\mathbf{X}^{1:n}) < \delta\}$$

$$\|\tilde{\mathbf{v}}(n|n)\| \in \mathcal{V}$$

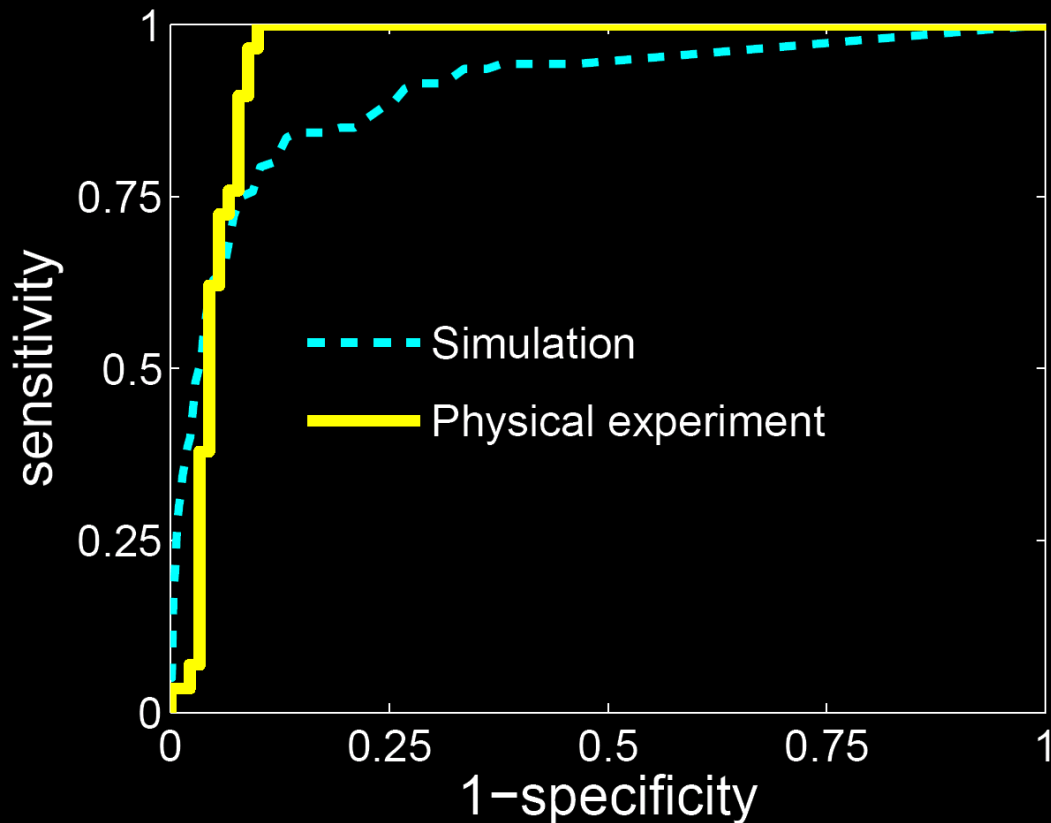


Experiments and Results

- Testing phase: May 2006 to Oct. 2006 in Texas A&M campus
- Field phase: Oct. 2006 to Oct. 2007 in Brinkley, AR



ROC Curves for Rock Pigeon



Area under ROC curve: 91.5% in Simulation; 95.0% in Experiment.









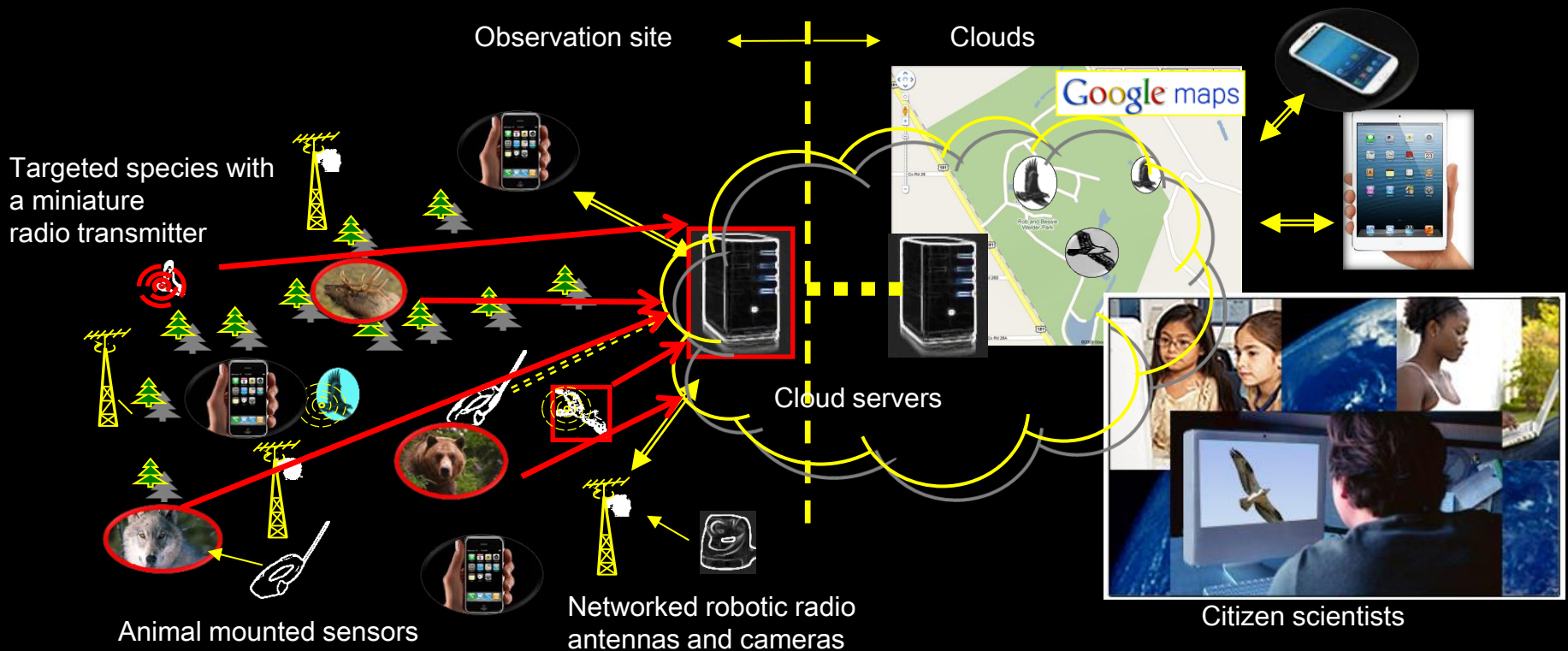




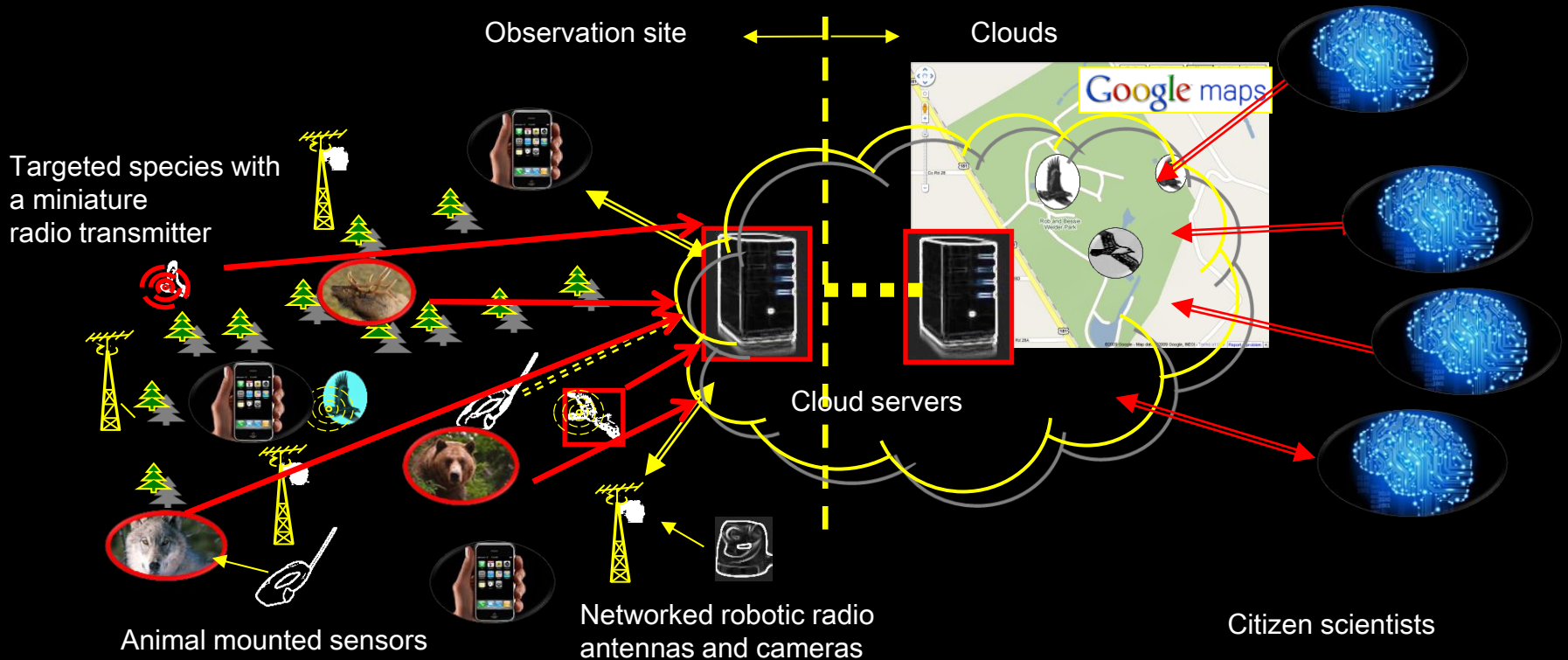
Results:

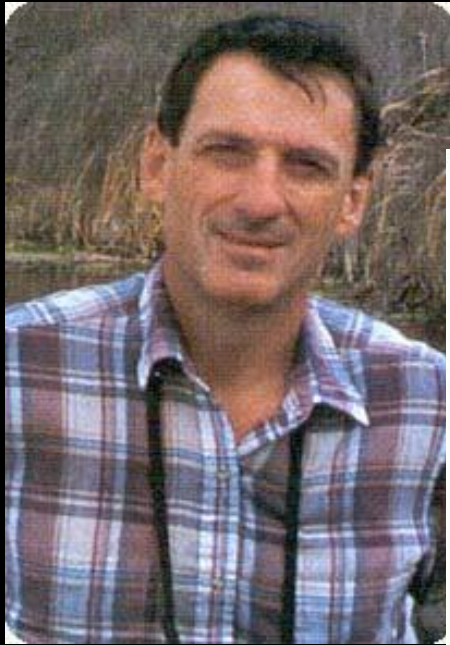
- **No Ivory-billed Woodpecker!**
- Sensitivity: <10% false negative rate
- Data reduction:
 - 146.7MB out of 29.41TB raw data
 - data reduction rate 99.9995%
- Robustness: running continuously in the Arkansas wilderness for 12 months

Robotic BioTelemetry



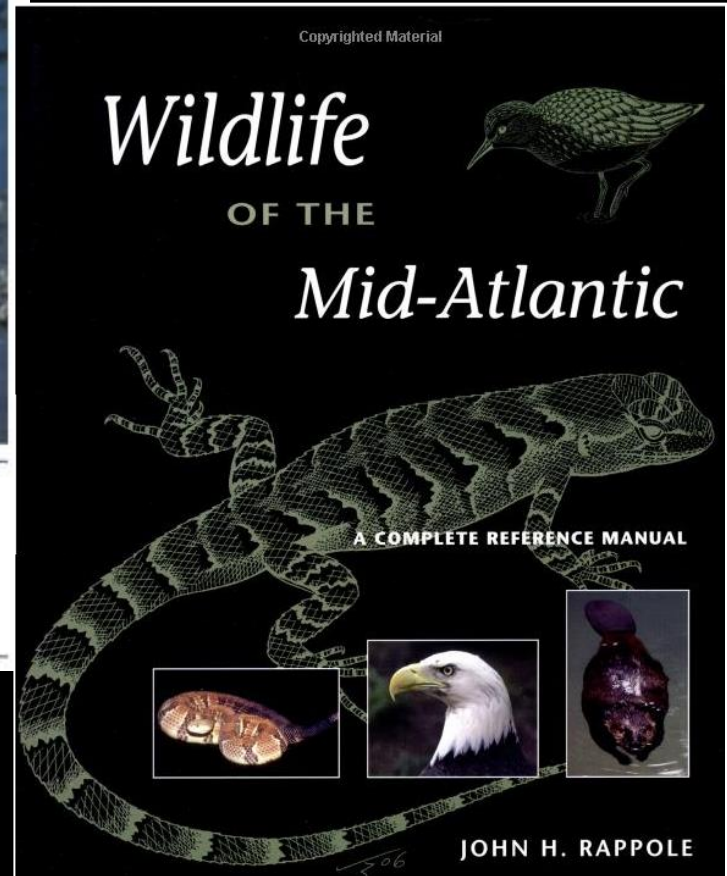
Crowd Sourcing Collaborative Computing





*Birds of the Texas Coastal Bend
Abundance and Distribution*

by John H. Rappole AND Gene W. Blacklock





Welcome Chat Gallery Score Statistics

Refresh prev 1 / 3574 next Show Categories

11/26/08 10:46am



txbird #118280

11/26/08 10:28am



kryptonkay #118267

11/26/08 10:23am



kryptonkay #118264

11/26/08 10:22am



vanilla #118259

11/26/08 10:22am



peteinkeyworth #118258

11/26/08 10:22am



vanilla #118252



 **CONE WELDER**

COLLABORATIVE OBSERVATORIES FOR NATURAL ENVIRONMENTS
Please email support.cone.welder@gmail.com with problems/suggestions/etc.
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2/19/09 9:47am by kryptonkay

Rating(5) ★ ★ ★ ★ ☆



Northern Cardinal / *Cardinalis cardinalis*

Animal:

Birds

Name:

Northern Fulmar / *Fulmarus glacialis*



Return

Northern Fulmar / *Fulmarus glacialis*

classify

eyes23blue says:

beautiful! the colour and the pose! *-*

vanilla says:

Sweet!

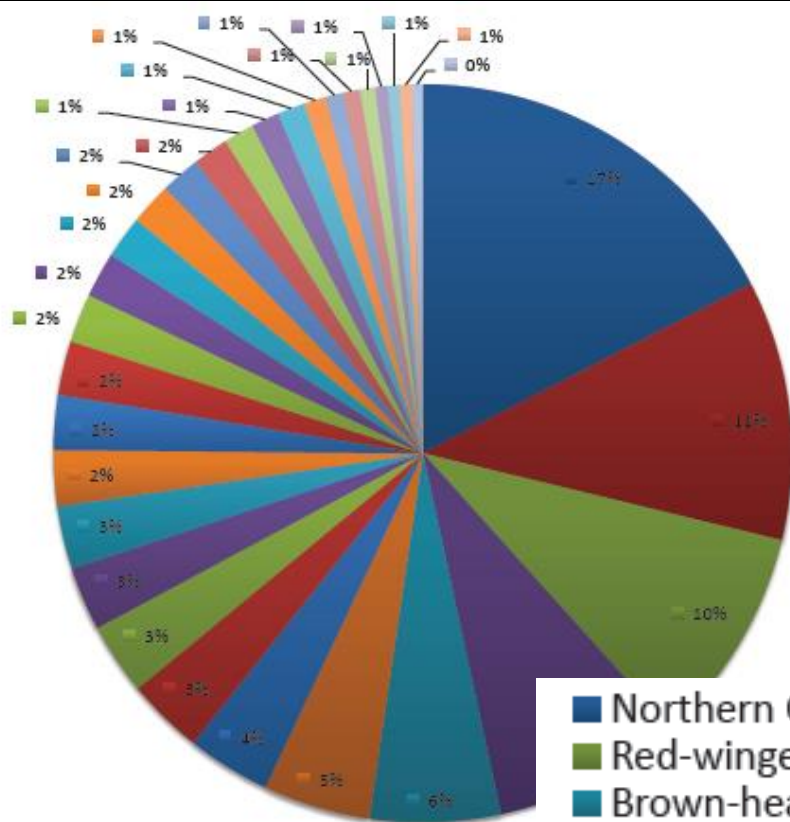
birdbrain says:

Great!!!

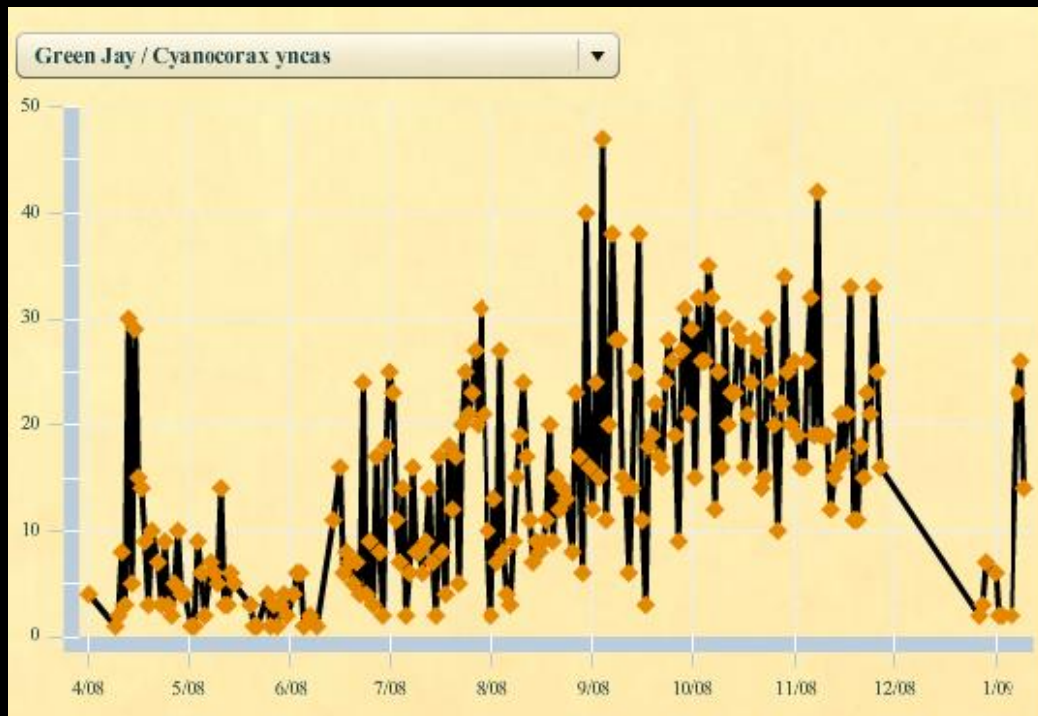
avatar99 says:

Nice one, KK

Add Comment



- | | |
|-----------------------------|-----------------------------|
| ■ Northern Cardinal | ■ Green Jay |
| ■ Red-winged Blackbird | ■ Inca Dove |
| ■ Brown-headed Cowbird | ■ White-tail Deer |
| ■ Javelina | ■ Bronzed Cowbird |
| ■ No Classifiable Species | ■ Raccoon |
| ■ Buff-bellied Hummingbird | ■ Chipping Sparrow |
| ■ Black-chinned Hummingbird | ■ Great-tailed Grackle |
| ■ Barred Owl | ■ Feral Hog |
| ■ Northern Mockingbird | ■ Ruby-throated Hummingbird |
| ■ American Goldfinch | ■ Fox Squirrel |
| ■ Golden-fronted Woodpecker | ■ Great Kiskadee |
| ■ Insect | ■ Painted Bunting |





Cliff Swallow



Brown-crested flycatcher



Laughing Gull



Painted Bunting



Veery



Eastern Wood-Pewee



Bonaparte's Gull



Scissor-tailed flycatcher



Yellow-crowned Night-Heron



Swallow-tailed Kite



Green jay



Least grebe



Common Moorhen



Crested Caracara



Great Egret



Plain chachalaca



Great egret



Magnolia warbler



Turkey Vulture



Savannah Sparrow



Wilson's Snipe



Great kiskadee



Marbled Godwit



Black and White Warbler



Orchard Oriole



Vermilion flycatcher



Snowy egret



Ring-billed Gull



Gray catbird



Barred Owl



King Rail



Green Kingfisher



Varied Bunting



Yellow warbler



Cactus wren



Great egret



Blue-winged teal



Mexican Jay



Purple gallinule



Brown Pelican



Red-tailed hawk



Whooping crane



Yellow-throated Warbler



American Bittern



Green heron



Chestnut-sided Warbler



Cackling Goose



Black-throated Green-Warbler



Sandwich Tern



Prothonotary warbler



Black Skimmer



Scarlet tanager



Eastern phoebe



Pyrrhuloxia



Roseate Spoonbill



Great-horned owl



Wilson's Plover



Red-headed Woodpecker



Northern cardinal



Red-shouldered Hawk



Brown jay



Northern quail



Great blue heron



Blackburnian warbler



Eared grebe



Pied-billed grebe



American goldfinch



American kestrel



American crow



American robin

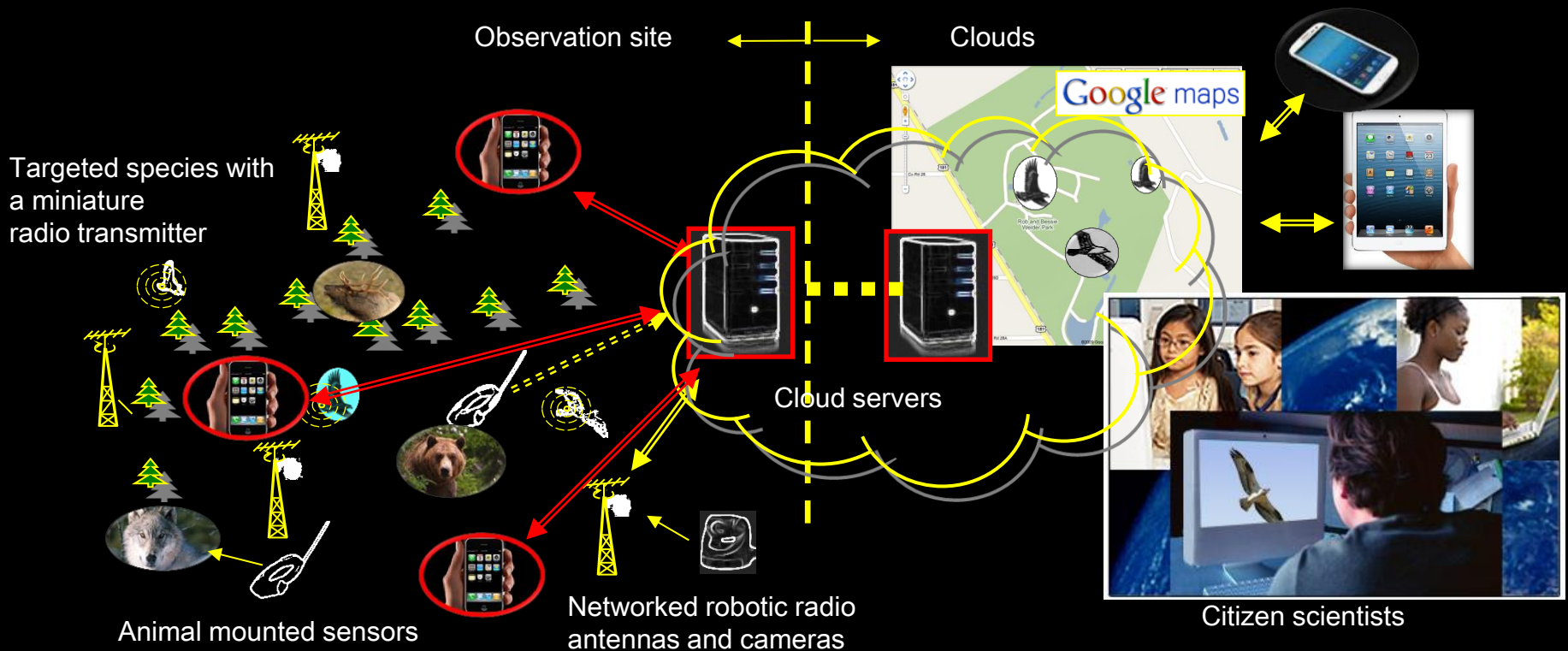


American osprey



American woodcock

Crowd Sourcing for Ubiquitous Observation

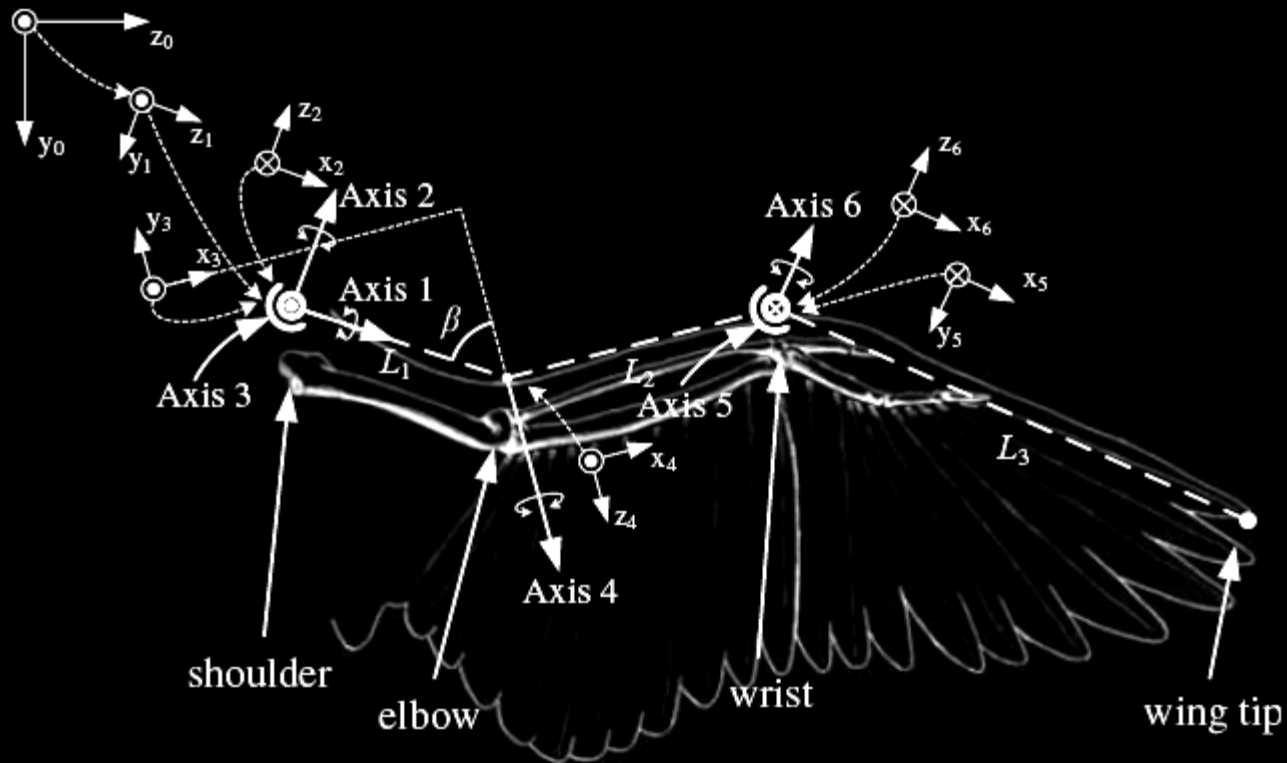


Crowd Sourced Videos

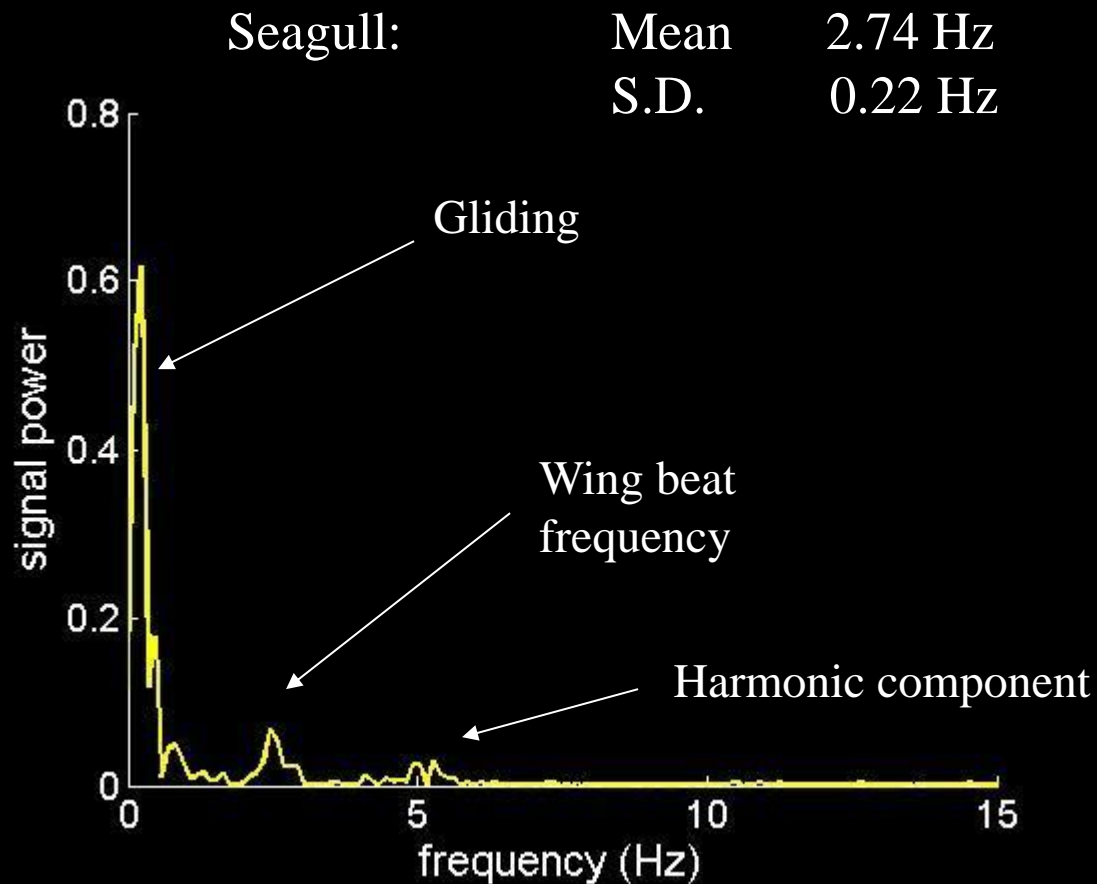
- Examine wing-flapping motion
 - Wing beat frequency is unique for each species



Wing Kinematic Model

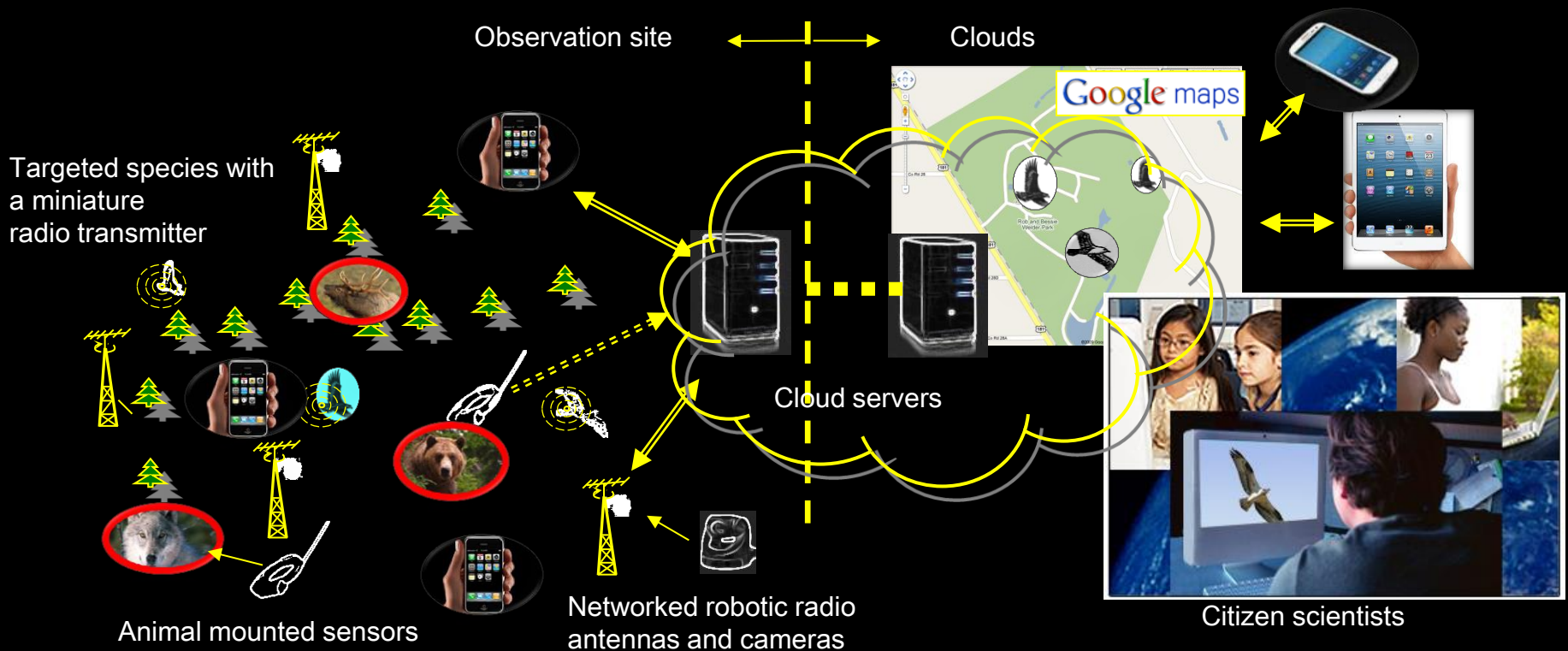


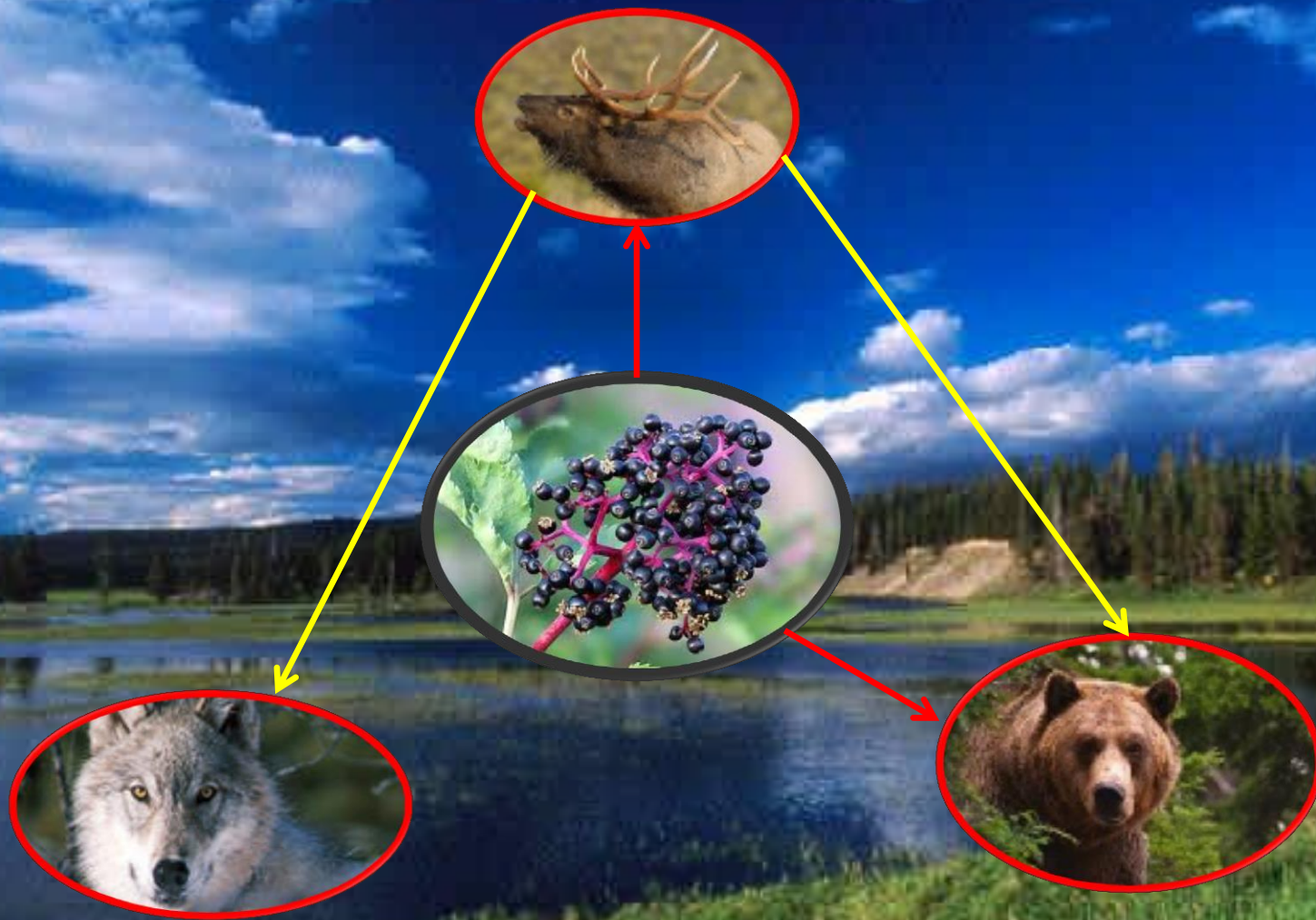
Sample Results

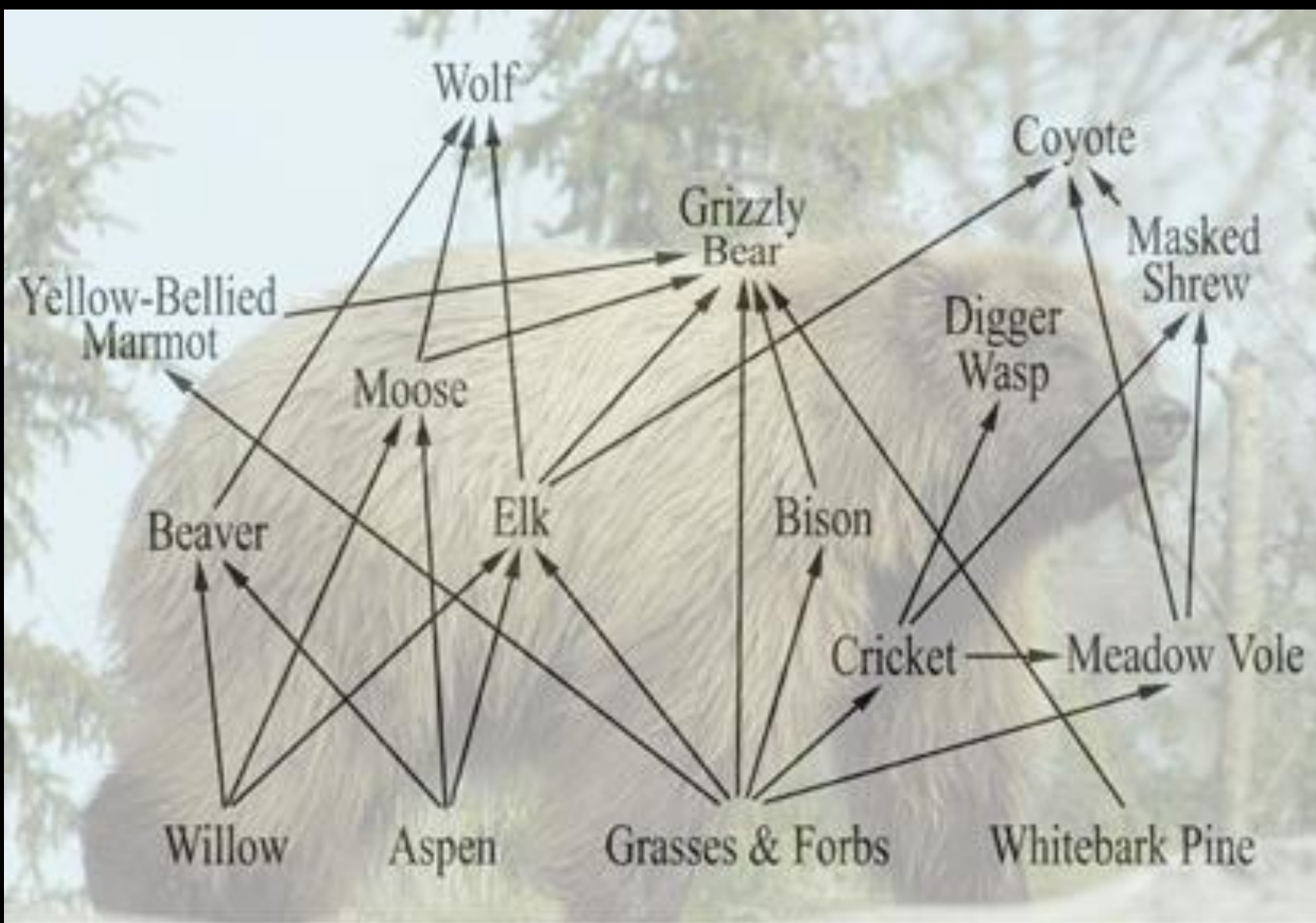


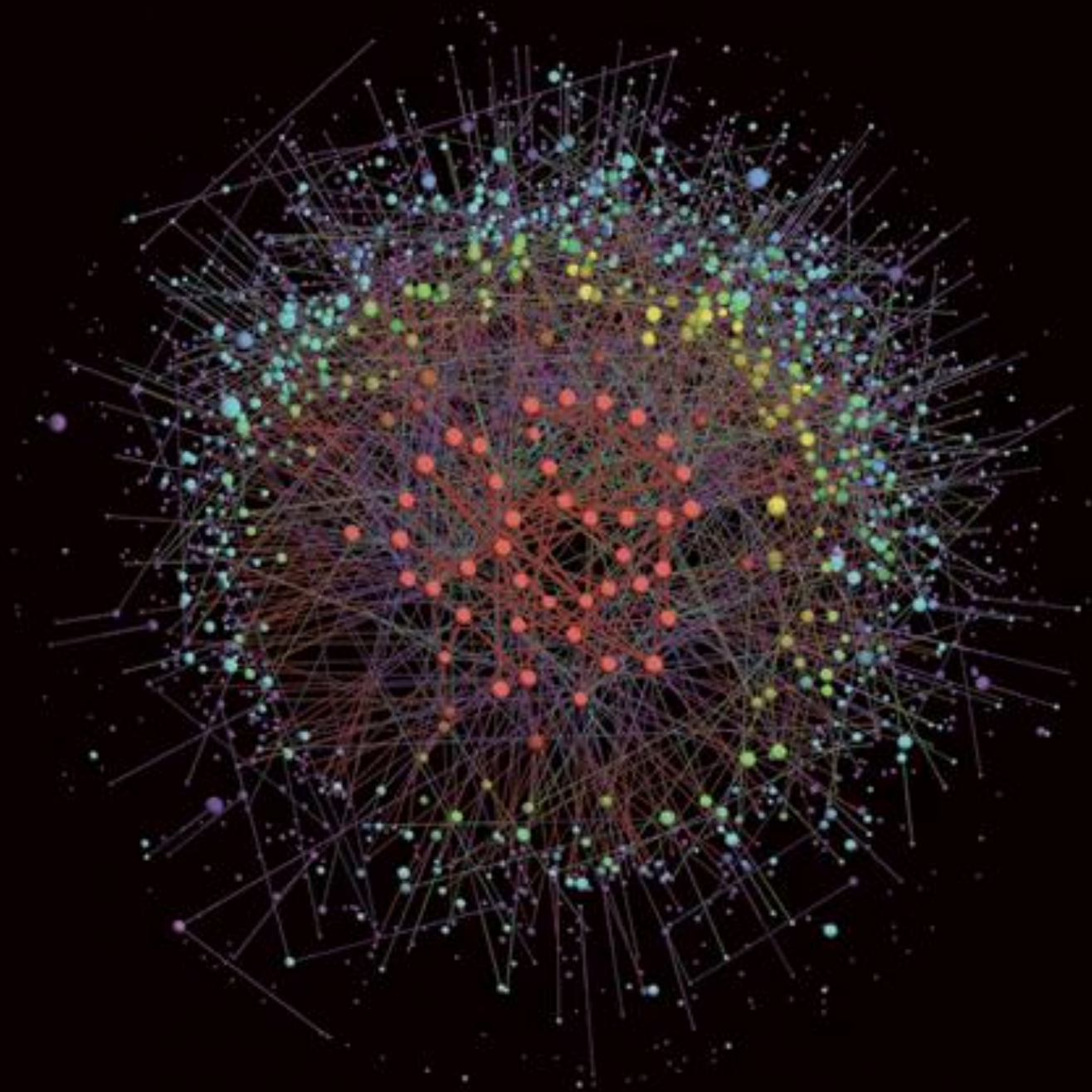
Wen Li and Dezhen Song, *Automatic Bird Species Detection from Crowd Sourced Videos*, IEEE Transactions on Automation Science and Engineering (T-ASE) (Accepted, To appear)

What is More about Cloud?





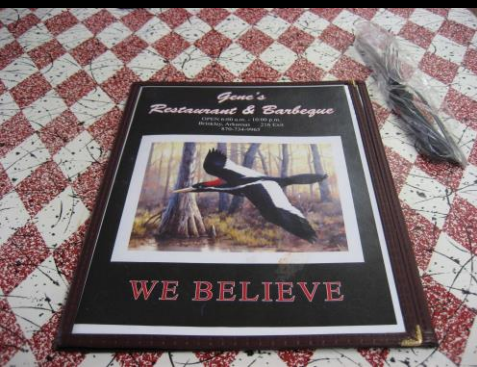




Cloud Science?

- Understanding system of systems
 - Integrating sensor/robot/human
 - Large scale AND fine granularities
 - Identifying relationships between isolated observations
 - Modeling, model generation, model verification at different granularities
 - Prediction: Recognizing “Butterfly Effect”





Thanks!

Websites:

<http://telerobot.cs.tamu.edu>

<http://rbt.cs.tamu.edu/>



Assumptions

- Static monocular camera
 - High resolution
 - Narrow FOV



- Single bird in FOV
 - Motion segmentation

- Constant bird velocity
 - High flying speed
 - Narrow camera FOV

